### Assisted Object Placement

Master's Thesis – Andreas Kirsch



#### Motivation



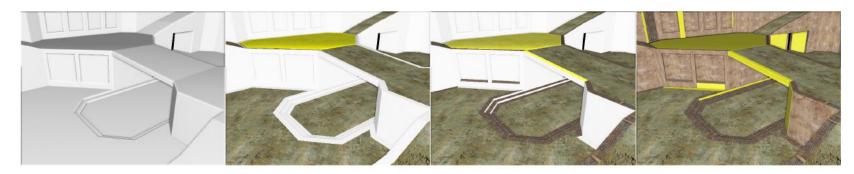
### Background





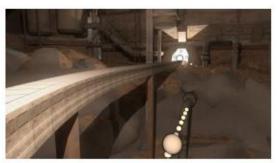


## Background









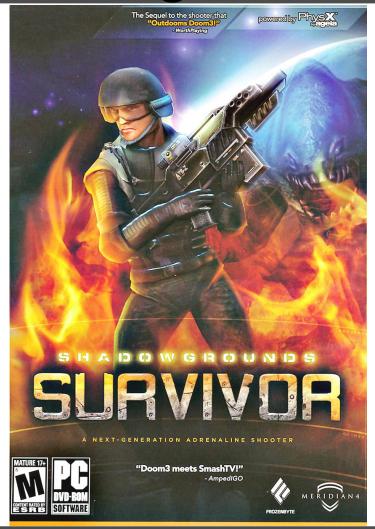








### Shadowgrounds Survivor

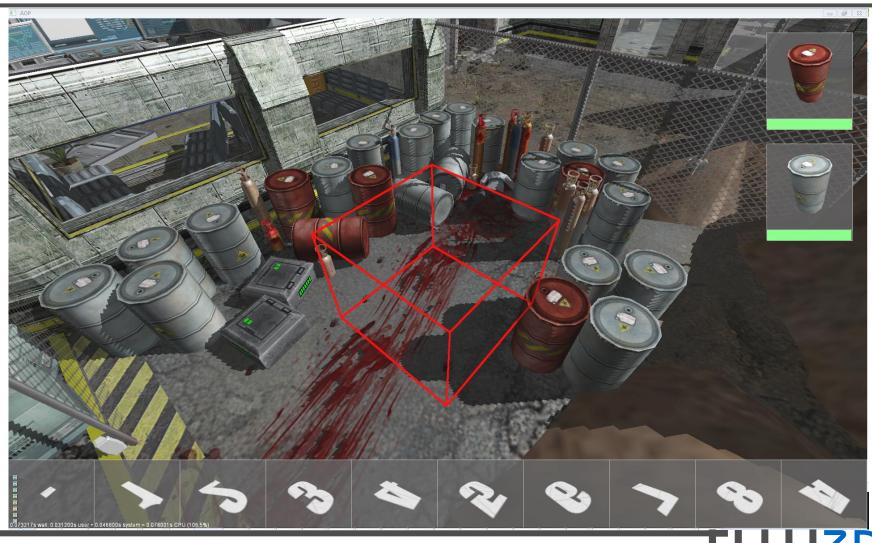




### Goals

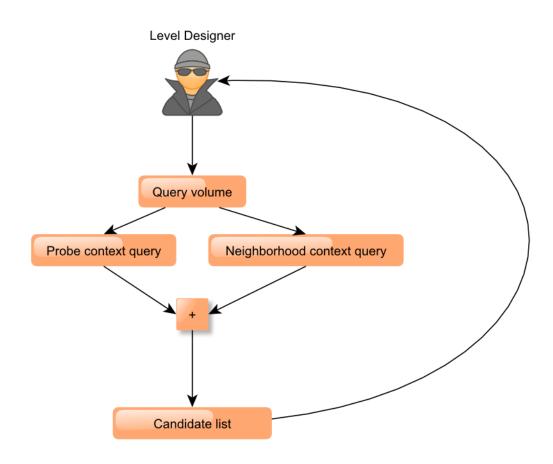


### Goals



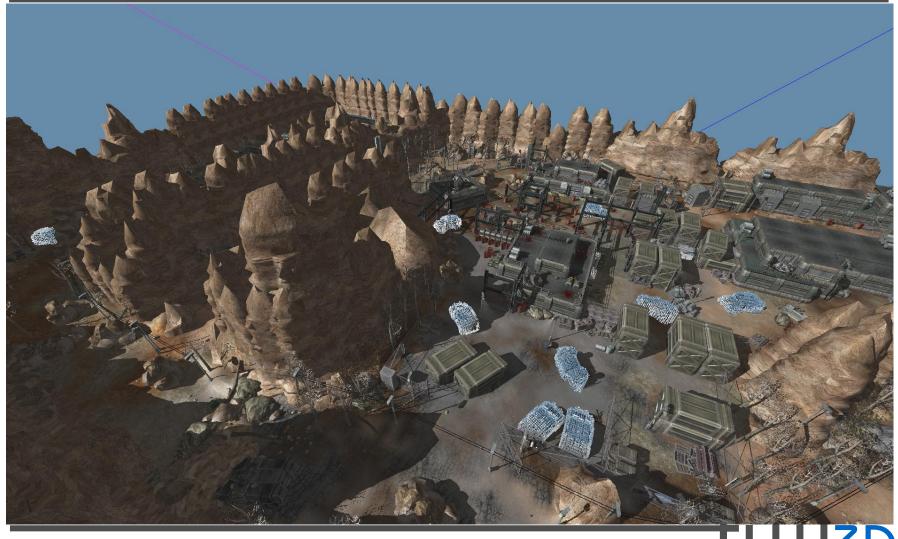
Assisted Object Placement Andreas Kirsch

#### Overview



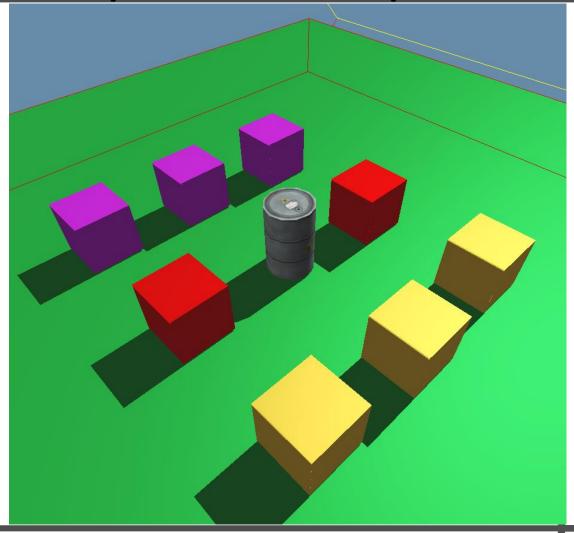


### Probe context

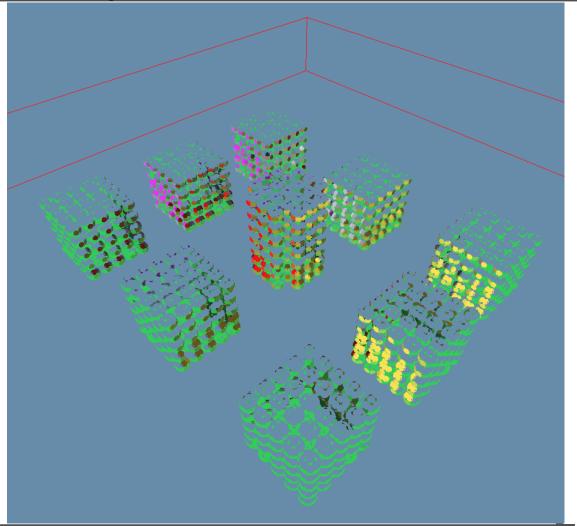


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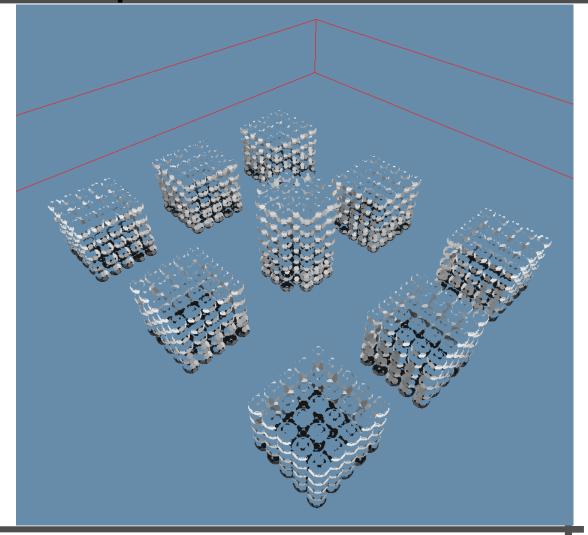
# Probe samples – Example



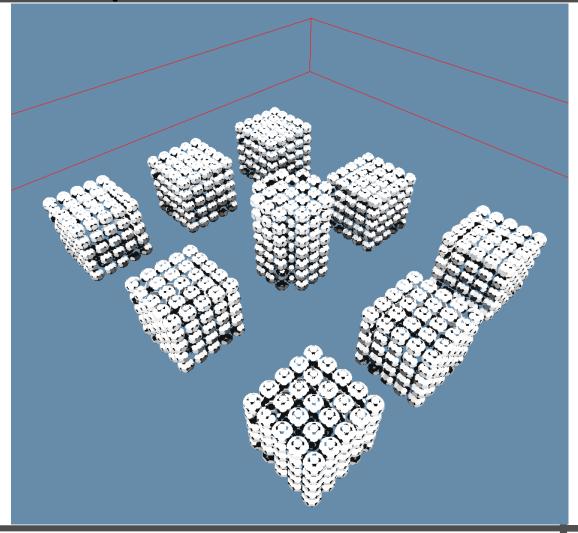
### Probe samples – Color



## Probe samples – Distance



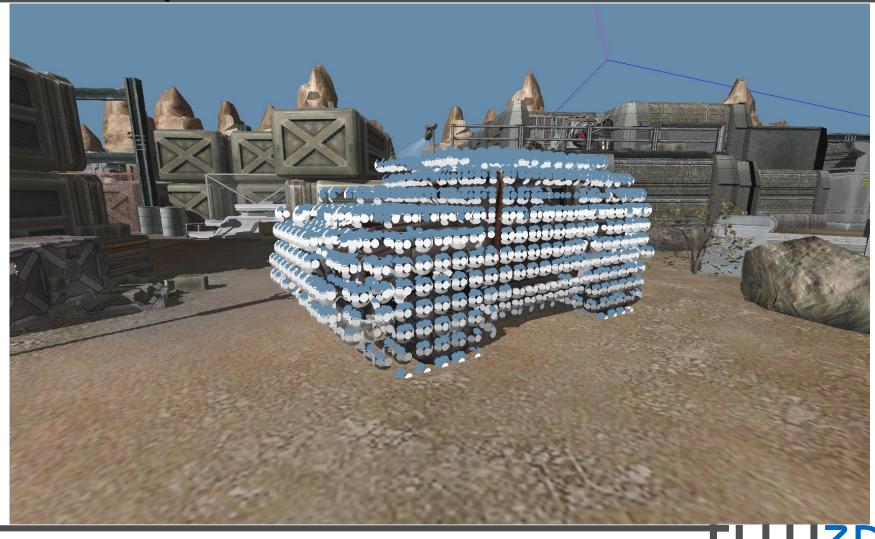
### Probe samples – Occlusion



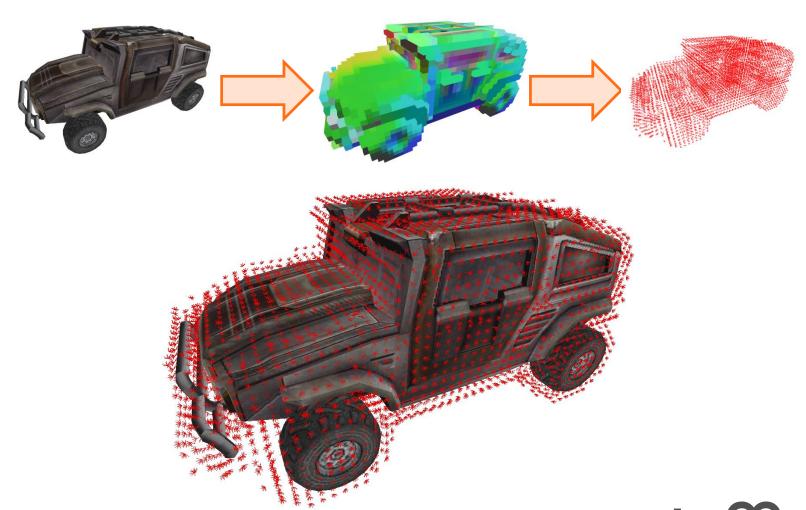
# Probe placement



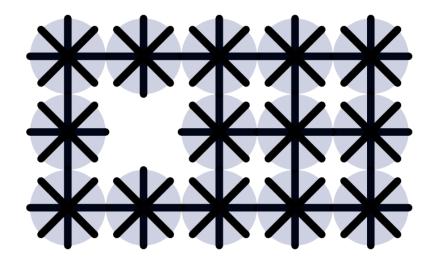
## Probe placement



### Probe placement

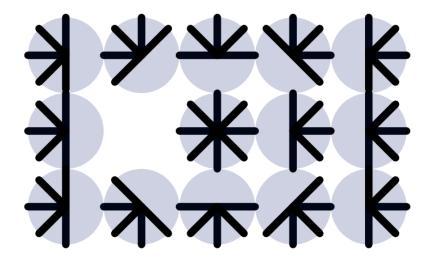


#### Probe placement – All directions



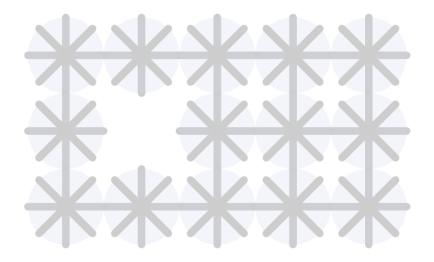


### Probe placement – Relative position



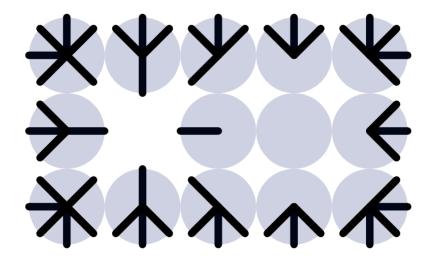


### Probe placement – Neighbors



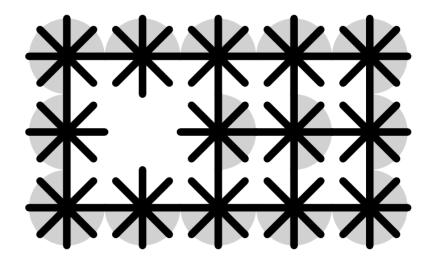


#### Probe placement – Neighbors



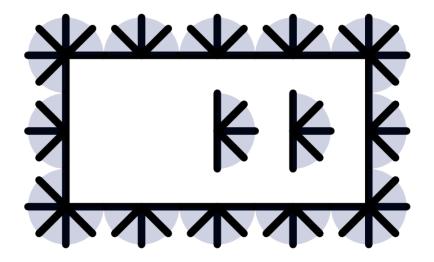


#### Probe placement – Avg normals



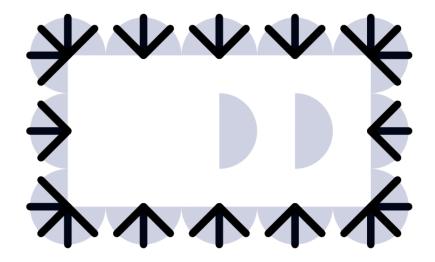


#### Probe placement – Avg normals





#### Probe placement – Combined



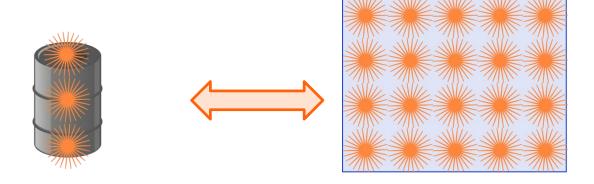


## Queries



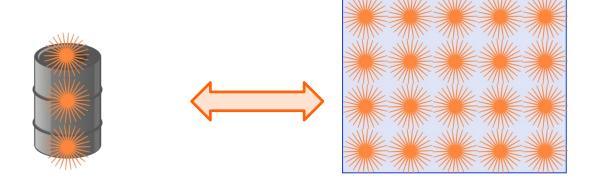


### Bidirectional match query





#### Bidirectional match query

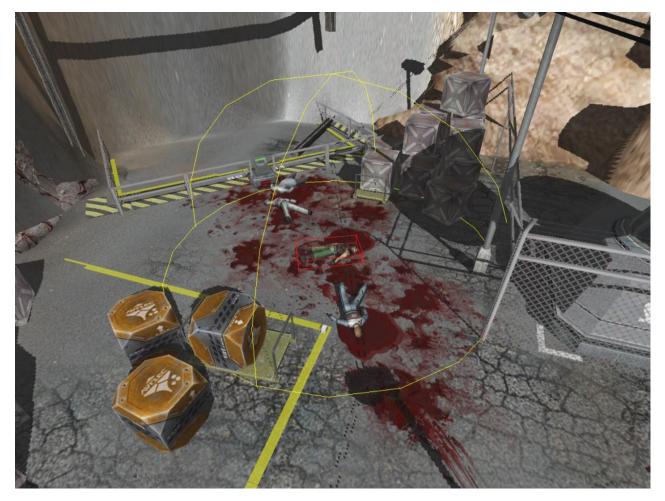


$$S = \frac{\# \text{matches model}}{\# \text{samples model}}$$

#matches query #samples query

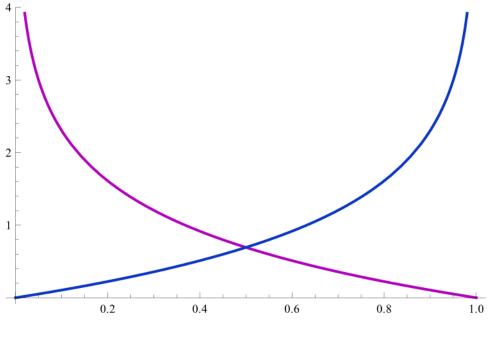


## Importance-weighted queries





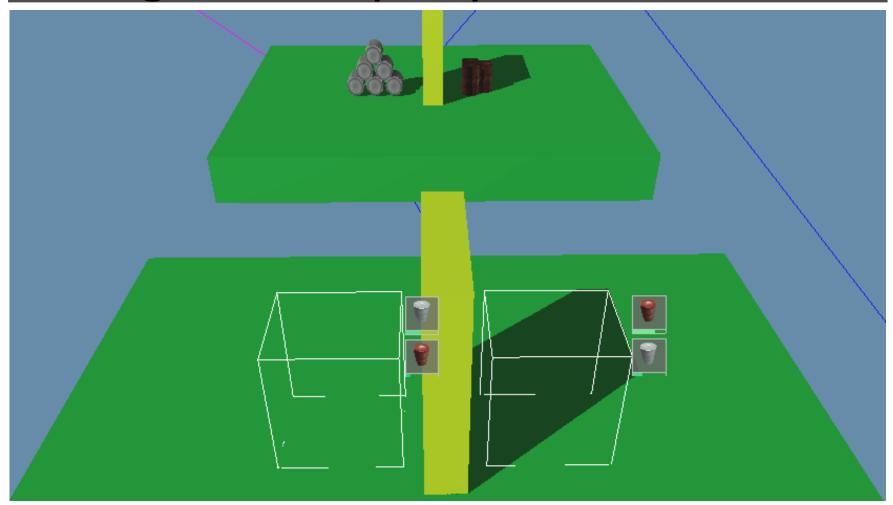
### Importance-weighted queries



$$h(X) = -\ln P(X)$$

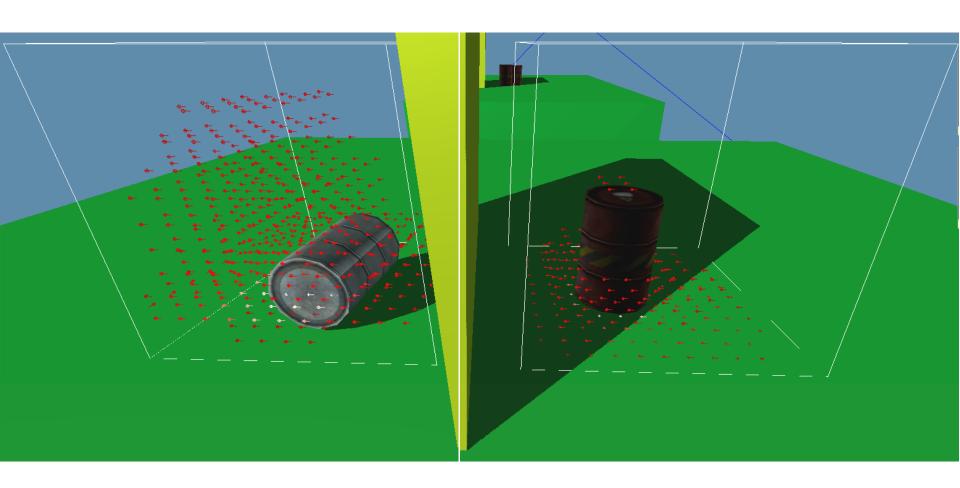


Configuration query



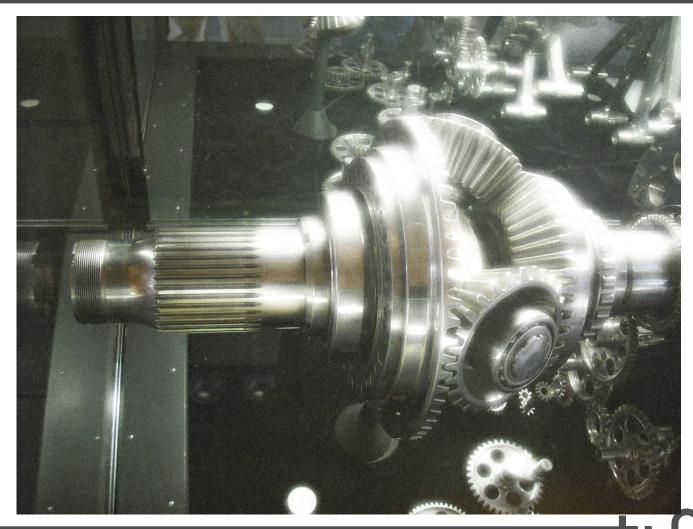


## Configuration query

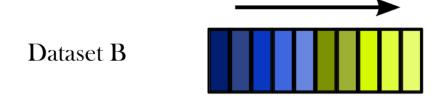


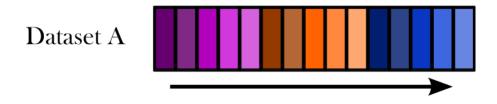


# **Algorithms**



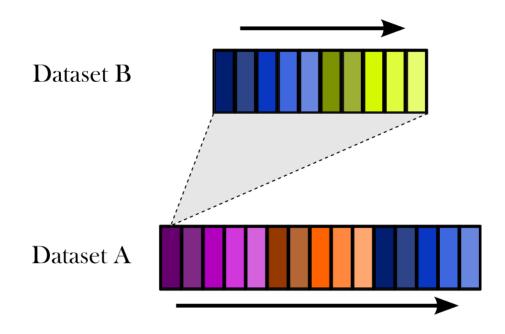
### Naive implementation





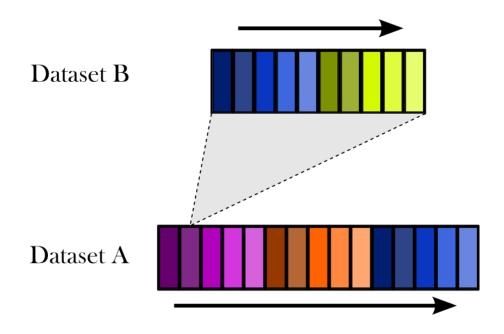


## Naive implementation





## Naive implementation





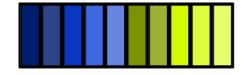
### **Optimizations**





### First optimization

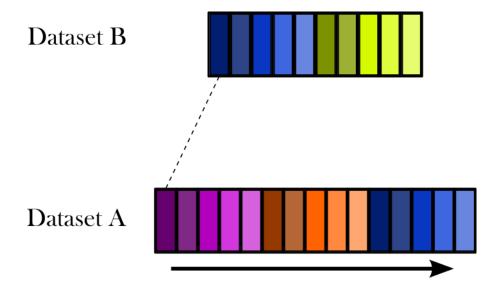
Dataset B



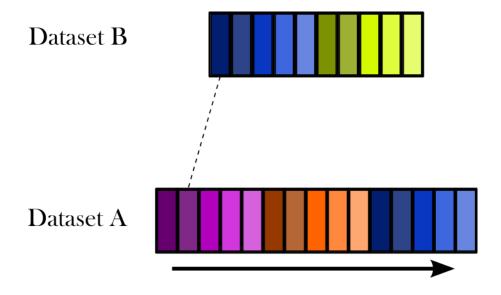
Dataset A



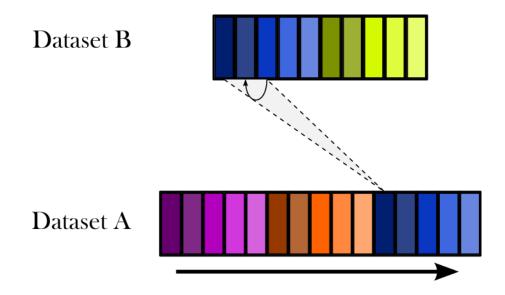




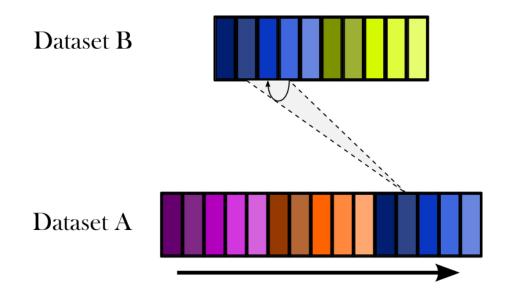








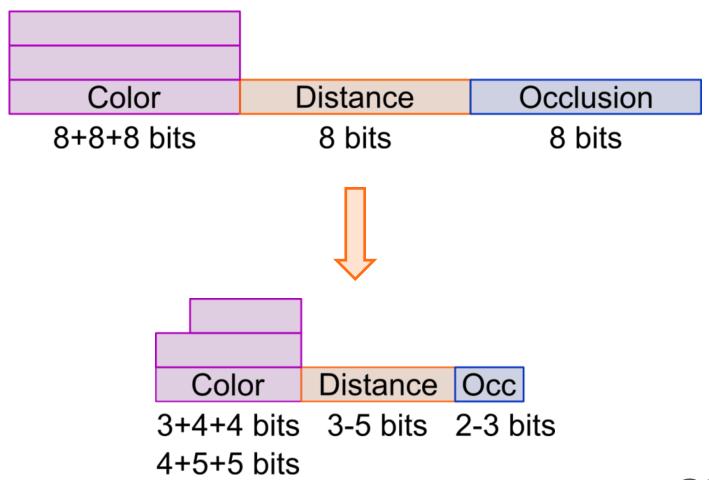






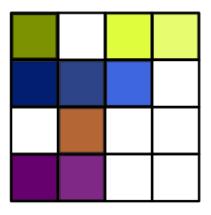






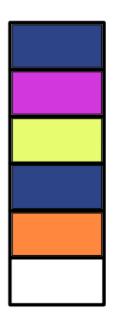


Packed probe sample bit set



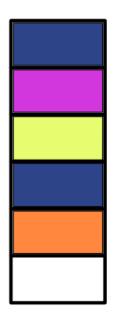


# Packed probe sample sequence

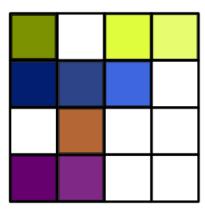




#### Sampled model

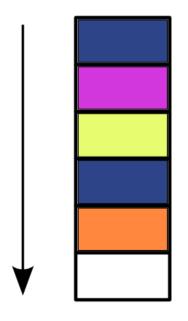


#### **Query volume**

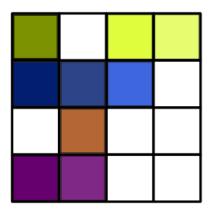




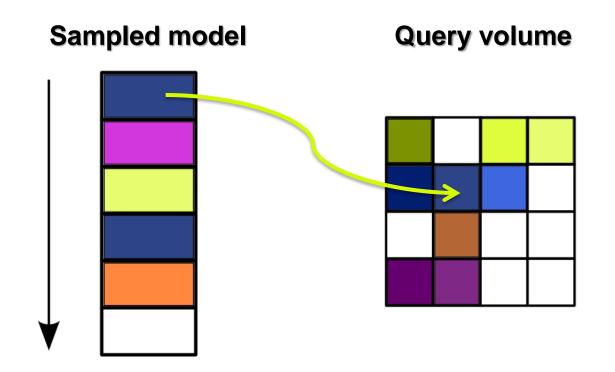
#### Sampled model



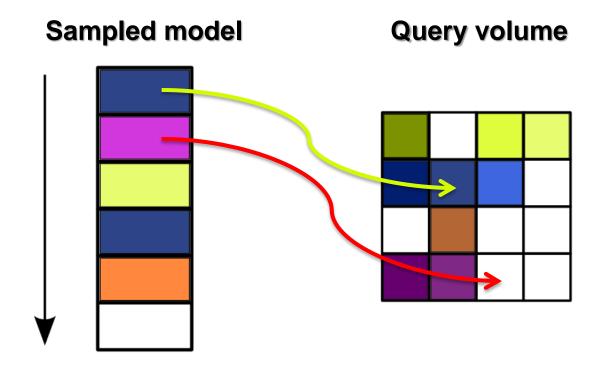
#### **Query volume**



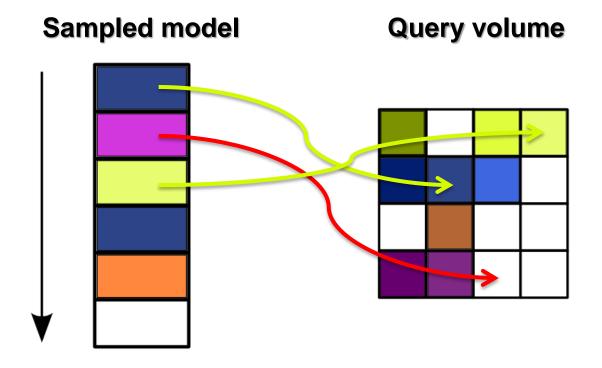




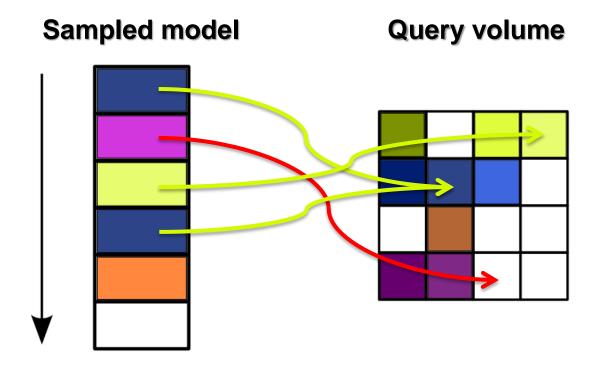




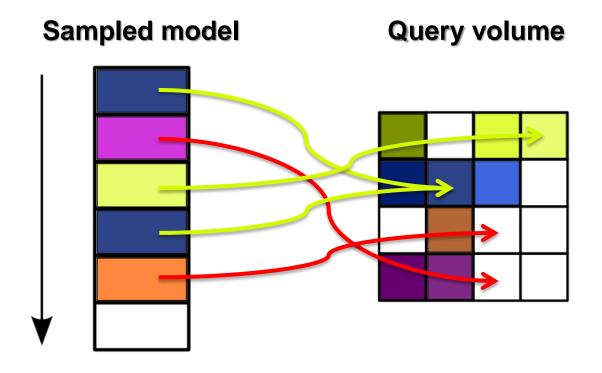






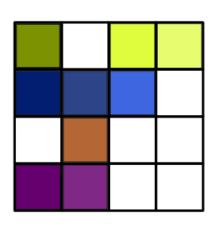




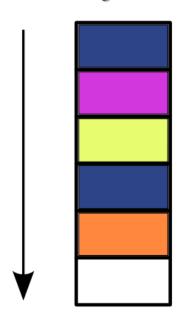




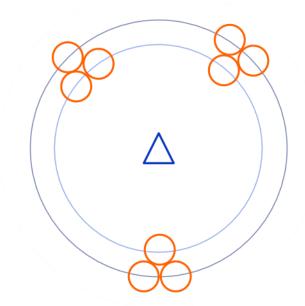
#### Sampled model



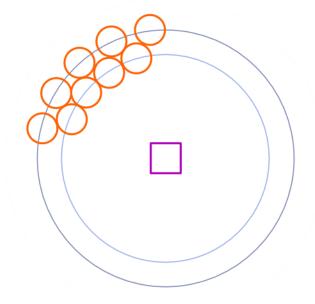
#### **Query volume**



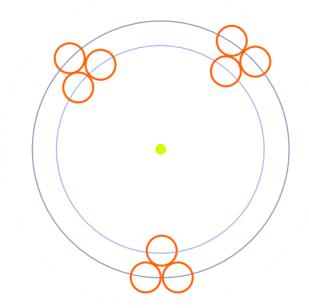




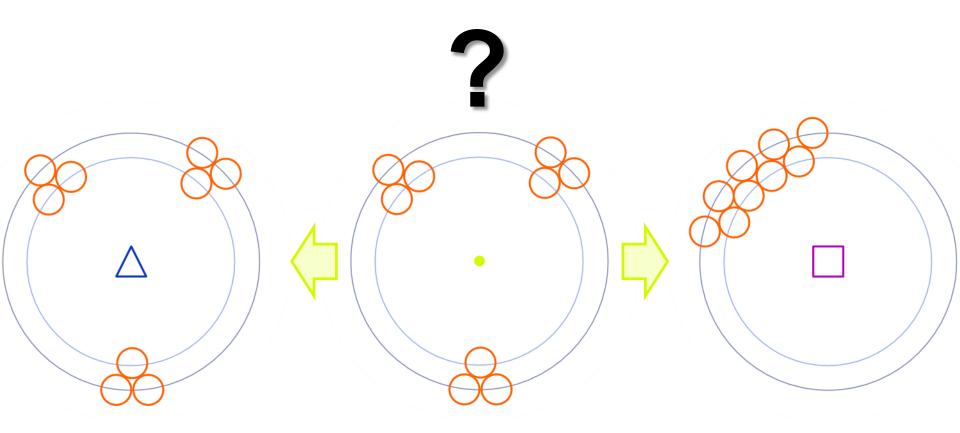






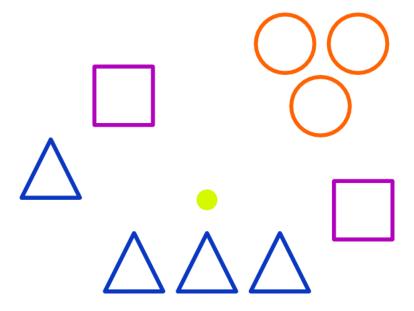






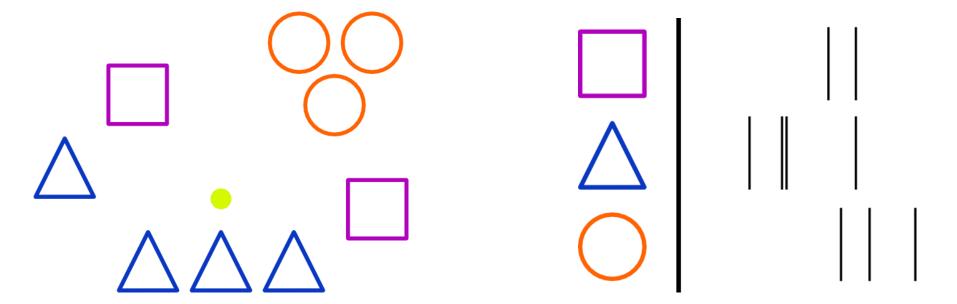


## Comparing neighborhoods



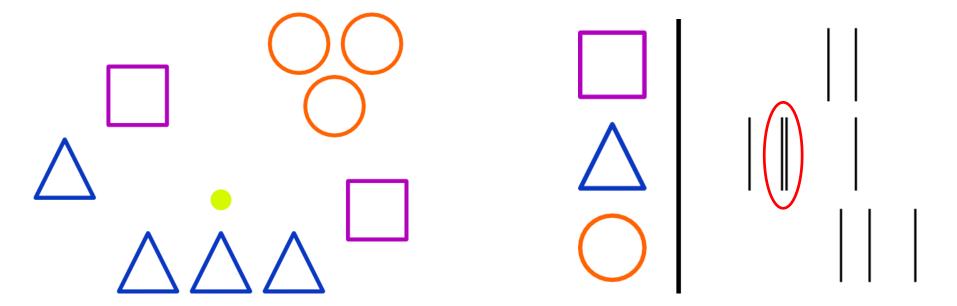


### Comparing neighborhoods

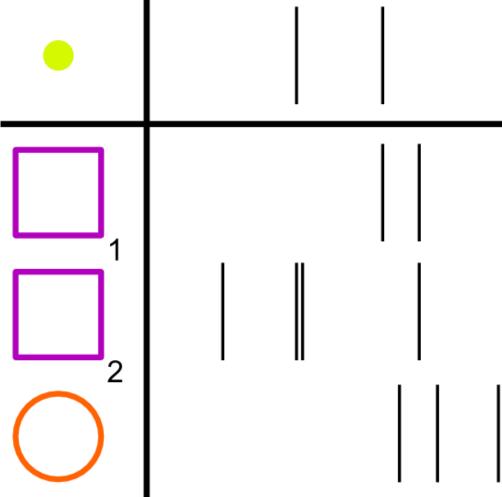


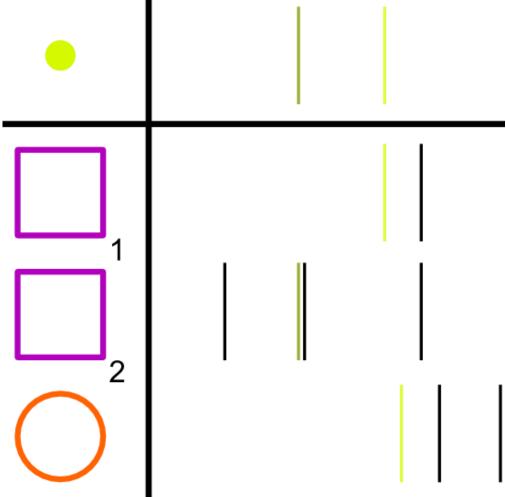


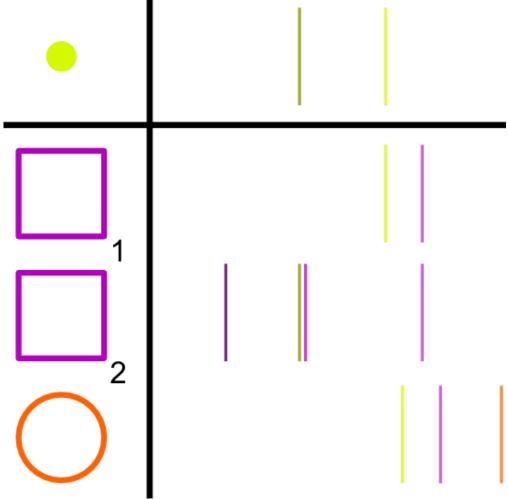
### Comparing neighborhoods

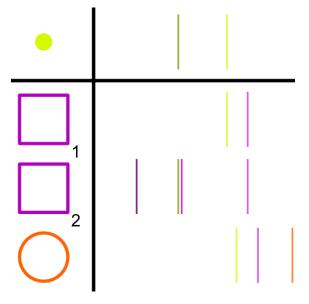




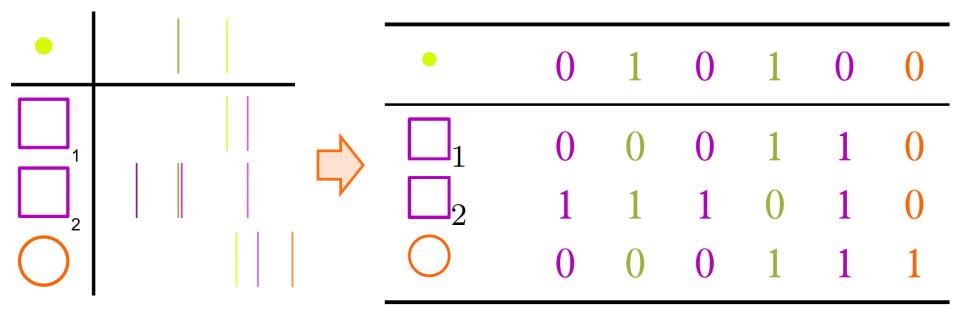














# Similarity measures

•	0	1	0	1	0	0
$\square_1$	0	0	0	1	1	0
$\square_2$	1	1	1	0	1	0
	0	0	0	1	1	1

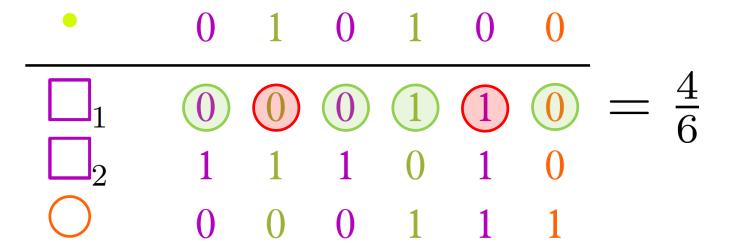


$$R = \frac{m_{11} + m_{00}}{m_{11} + m_{10} + m_{01} + m_{00}}$$

•	0	1	0	1	0	0
$\square_1$	0	0	0	1	1	0
$\square_2$	1	1	1	0	1	0
	0	0	0	1	1	1

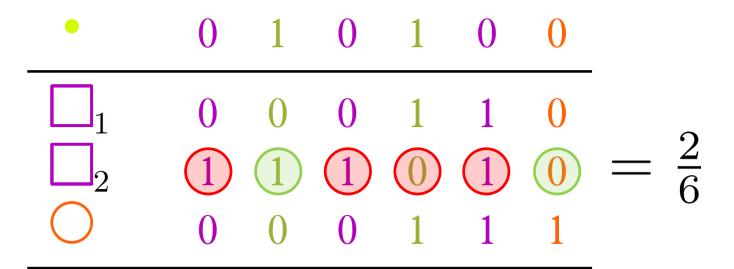


$$R = \frac{m_{11} + m_{00}}{m_{11} + m_{10} + m_{01} + m_{00}}$$





$$R = \frac{m_{11} + m_{00}}{m_{11} + m_{10} + m_{01} + m_{00}}$$





$$R = \frac{m_{11} + m_{00}}{m_{11} + m_{10} + m_{01} + m_{00}}$$

•	0	1	0	1	0	0		
$\Box_1$	0	0	0	1	1	0		
$\square_2$								0
	0	0	0	1	1	1	=	$\frac{3}{6}$



#### Jaccard index

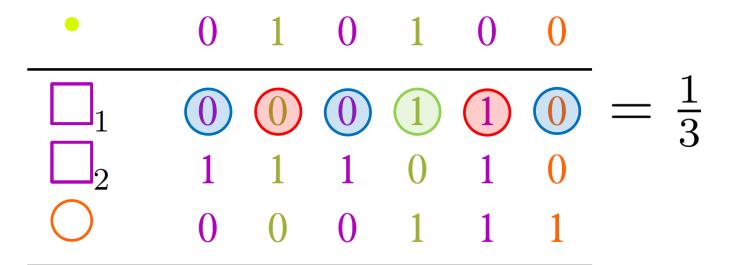
$$R = \frac{m_{11}}{m_{11} + m_{10} + m_{01}}$$

•	0	1	0	1	0	0
$\Box_1$	0	0	0	1	1	0
$\square_2$	1	1	1	0	1	0
	0	0	0	1	1	1



#### Jaccard index

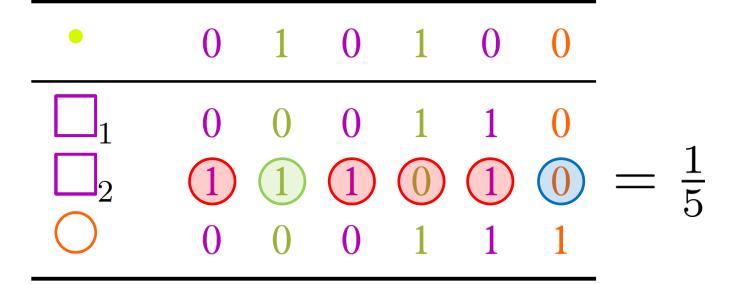
$$R = \frac{m_{11}}{m_{11} + m_{10} + m_{01}}$$





#### Jaccard index

$$R = \frac{m_{11}}{m_{11} + m_{10} + m_{01}}$$





#### Jaccard index

$$R = \frac{m_{11}}{m_{11} + m_{10} + m_{01}}$$





$$R = rac{\sum \Phi_k \, 1\!\! 1_{\{ ext{query}_k = ext{instance}_k\}}}{\sum \Phi_k}$$
 $\bullet$ 
 $0 \quad 1 \quad 0 \quad 1 \quad 0 \quad 0$ 
 $\square_1 \quad 0 \quad 0 \quad 0 \quad 1 \quad 1 \quad 0$ 
 $\square_2 \quad 1 \quad 1 \quad 1 \quad 0 \quad 1 \quad 0$ 
 $\bigcirc \quad 0 \quad 0 \quad 1 \quad 1 \quad 1$ 



$$R = \frac{\sum \Phi_k \, \mathbb{1}_{\{\text{query}_k = \text{instance}_k\}}}{\sum \Phi_k}$$

- 0 1 0 1 0
- - 0 0 0 1 1 1



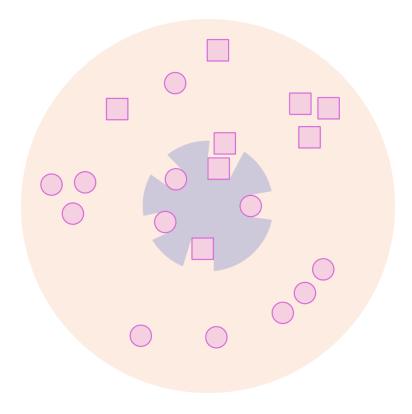
$$R = \frac{\sum \Phi_k \, \mathbb{1}_{\{\text{query}_k = \text{instance}_k\}}}{\sum \Phi_k}$$

- 0 1 0 1 0 0
- $\Box_1$  0 0 0 1 1 0



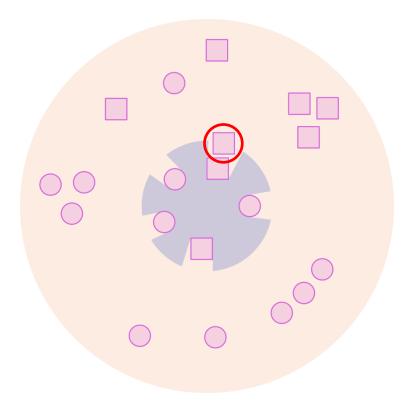


# Combining context scores



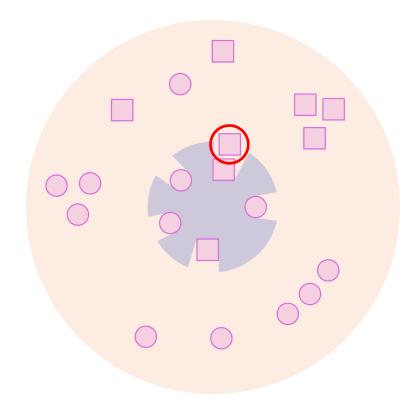


# Combining context scores





## Combining context scores



$$S_{\text{final}} = S_{\text{probe}} \cdot S_{\text{neighborhood}}$$



## Results

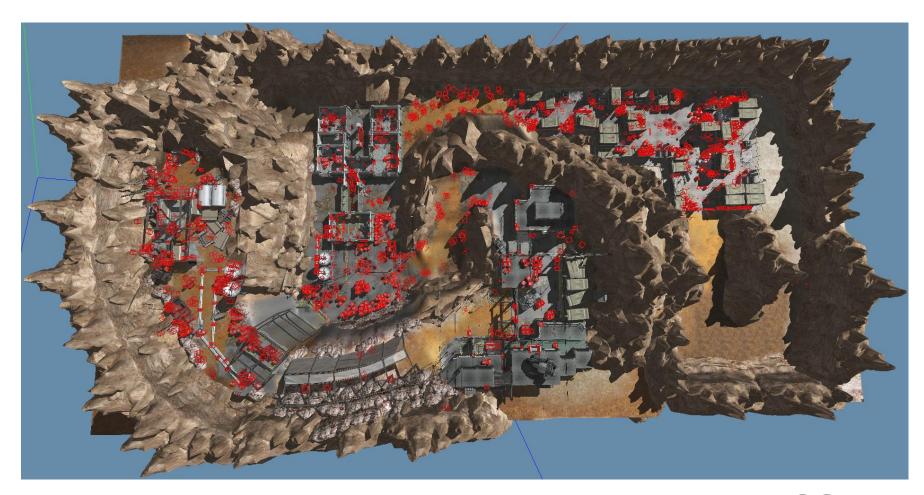




## Validation

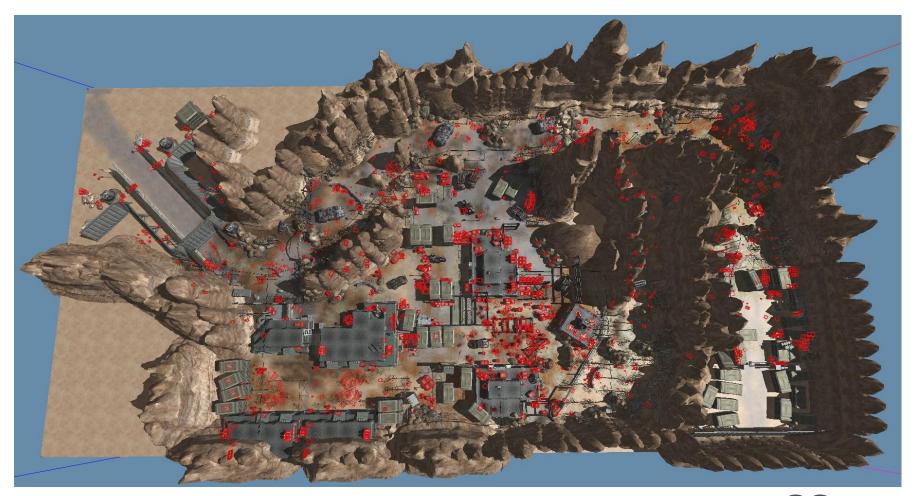


# marine01\_wakeup





# marine02 road





# Validation: probe context

	# models	# instances	avg rank (model frequency)
marine02_road	94	1396	17.15
marine01_wakeup	150	2066	21.10

Level	marine02_road	marine02_road(5)	marine01_wakeup
Uniform bidirectional match	14.1	17.7	15.2
IW bidirectional match	12.9	17.6	14.3
Configuration	10.5	16.0	10.4



# Validation: neighborhood context

	# models	# instances	avg rank (model frequency)
marine02_road	94	1396	17.15
marine01_wakeup	150	2066	21.10

Max random shift		2			4			8	
Max distance	10	20	60	10	20	60	10	20	60
Rand measure	0.38	0.43	0.46	1.16	1.20	1.23	3.38	2.90	2.91
IW measure	0.40	0.42	0.45	1.23	1.21	1.21	3.57	2.92	2.90
Jaccard index	0.38	0.43	0.46	1.14	1.20	1.23	2.86	2.88	2.90



#### Validation: combined contexts

	# models	# instances	avg rank (model frequency)
marine02_road	94	1396	17.15
marine01_wakeup	150	2066	21.10

	marine02_road		marine02_road $(5)$			marine01_wakeup			
	Rand	IW	Jaccard	Rand	IW	Jaccard	Rand	IW	Jaccard
Uniform bidirectional	7.14	11.0	0.230	7.34	12.6	0.176	8.85	12.3	0.651
IW bidirectional	8.09	11.0	0.399	9.81	14.4	0.320	9.79	12.5	0.926
Configuration	11.1	11.5	4.40	15.9	16.5	5.83	21.8	22.2	15.2



## Performance

	Rand measure	Importance-weighted measure	Jaccard index
marine02_road	9.5	11	9.5
marine01_wakeup	38	44	39

	Bidirectional query	IW bidirectional query	Configuration query
marine02_road	1.2	5.4	900
marine02 $\_$ road (5)	14	93	18000
marine01_wakeup	2.4	11	1500



# Summary



## Post Mortem



# Questions?



## Demo

